

### MDHP Series High Performance Variable Frequency Drive

**DeviceNet Option Manual** 

R S S





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Before using the product, thank you for purchasing MDLV-HP DeviceNet option board.

# SAFETY PRECAUTIONS

- Always follow safety instructions to prevent accidents and potential hazards from occurring.
- Safety precautions are classified into "WARNING" and "CAUTION" and their meanings are as follows:



Improper operation may result in serious personal injury or death.

Improper operation may result in slight to medium personal injury or property damage.

• The indicated illustrations on the product and in the manual have the following meanings.



Danger may be present. Read the message and follow the instructions carefully.



Particular attention should be paid because danger of an electric shock may be present.

- Keep operating instructions handy for quick reference.
- Read the operating instructions carefully to fully understand the functions of the MDLV-iP5A series and to use it properly.

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- Be cautious, when handling the CMOS components of the Option Board. Static may lead to malfunctioning of the product.
- Turn off the inverter power, when changing the communication cable. Otherwise, you may damage the board or a communication error may occur.
- Make sure to insert the Option Board connector to the inverter precisely. Otherwise, you may damage the board or a communication error may occur.
- Check the parameter unit before setting up the parameter. Otherwise, a communication error may occur.

### 1. Introduction

MDLV-HP DeviceNet communication card connect the MDLV-HP inverter with DeviceNet network. DeviceNet communication card enables the control and monitoring of inverter to be controlled by sequence program of PLC or Master module selected optionally.

As one or more inverters are connected and operated with a communication line, it can reduce the installation cost compared with when communication is not used. Furthermore, simple wiring enables to the reduction of installation period and easy maintenance as well.

A variety of peripheral devices such as PLC, etc. can be used to control the inverter, and factory automation is made easy by its advantage of the fact that it can be operated linked with a variety of systems such as PC, etc.

### 2. DeviceNet communication card specification

Terminology		Description			
	DeviceNet				
Dowor	communication	Supplied from inverter			
Supply	power source				
Supply	Exterior power	Input Voltage : 11 ~25V DC			
	source	Current consumption: Max. 60mA			
Network topology		Free, Bus Topology			
Communication Baud rate		125kbps, 250kbps, 500kbps			
		64 nodes (including Master), Max. 64 stations per each segment			
Max. numb	er of node	In the event of a Master node is connected to network, max.			
		number of the nodes connected is 63 nodes (64-1).			
Device type	Э	AC Drive			
		Explicit Peer to Peer Messaging			
Kind	of support	Faulted Node Recovery(Off-Line)			
communication		Master/Scanner (Predefined M/S Connection)			
		Polling			
Terminating resistor		120 ohm 1/4W Lead Type			

### 3. Communication Cable Specifications



For DeviceNet communication, DeviceNet standard cable specified by ODVA should be used. There are Thick or Thin type cable as DeviceNet standard cable. For DeviceNet standard cable, refer to ODVA homepage (<u>http://www.odva.org</u>).

Either Thick or Thin cable can be used for Trunk cable, but please use Thick cable in general. In case of Drop cable, use Thin cable is strongly recommended.

Maximum length of cable as below is the performance when DeviceNet standard cable was used.

Baud	Trunk Cal	ble length	Drop Length (Thin Cable)		
Rate	Thick Cable Thin Cable		Max. length	Total sum	
125 kbps	500 m (1640 ft.)			156 m (512 ft.)	
250 kbps	250 m (820 ft.)	100 m (328 ft.)	6 m (20 ft.)	78 m (256 ft.)	
500 kbps	100 m (328 ft.)			39m (128ft.)	

### 4. Installation

When unpacking DeviceNet communication card box, the contents consist of MDLV-HP communication card 1ea, Pluggable 5-pin connector 1ea, Lead type terminal resistor 120  $\Omega$  (1/4W) 1ea, bolt that fastens MDLV-HP DeviceNet communication card to MDLV-HP inverter, and this manual for MDLV-HP DeviceNet.

Layout of DeviceNet communication card is as below.



Installation figure is as below.



#### Instruction for installation)

Don't install or remove DeviceNet communication card with the power of inverter on. It may cause damages to both DeviceNet communication card and inverter. Be sure to install or remove communication card after the current of inverter's condenser has been completely discharged.

Don't change the connection of communication signal line with the power of inverter on. Be sure to connect the inverter body and the option board connector exactly corresponded with each other.

In the event of connecting of communication power source (24P, 24G), be sure to check they are V-(24G), V+(24P) silk of DeviceNet communication card before connecting them. When wiring is not connected correctly, it may cause the malfunction of communication.

When configuring the Network, be sure to connect the terminal resistor to the device that is connected with the end part. Terminal resistor should be connected between CAN\_L and CAN\_H. The value of terminal resistor is  $120 \Omega 1/4W$ .

## 5. LED

DeviceNet communication card enclose 2 LEDs mounted; MS (Module status) LED and NS (Network status) LED. Fundamental function of two LEDs is as below.

	It is used to check whether the power source state of DeviceNet					
MOLED	communication card is stable; whether CPU of DeviceNet communication					
Modulo	card is regularly operating; whether the interface communication between					
DeviceNet communication card and inverter body is made in smoot						
Status)	All the operations as above are normally made, MS LED will be lit in Solid					
	green.					
NS LED	It is used to indicate the connection of DeviceNet communication card to					
(Network	communication on the network or the network power source status.					
Status)						

### NS LED Status

LED	Status	Cause	Trouble shooting			
		5V power source is not	Check whether the inverter power			
		supplied to DeviceNet	source is supplied or 5V power			
		communication card.	source is supplied to DeviceNet			
Off	Off-Line		communication card			
	(No Power)	Checking of duplicated	Wait for 5 seconds at LED Off status			
		Mac ID	while checking duplicated MAC ID			
			after initializing of Option board at			
			power On.			
		Communication	Normal operation prior to			
		environment is ready	connecting.			
Flashing	On-Line	after checking				
Green	Not Connected	duplicated nodes but				
		any node is not				
		connected.				
Solid	On-Line,	Connection of one	Available to connect I/O			
Green	Connected	EMC or more is set up	communication (Poll)			
	(Link OK)					
Flashing	Connection Time-	Time out occurred	Inverter Reset			
Rod	Out	during Poll I/O	Request the reset service to Identity			
iteu	Critical Link Failure.	communication	Object and then re-connect I/O.			

LED	Status	Cause	Trouble shooting
		Duplicated MAC ID on	Change MAC ID set up.
		Network	
		Bus Off from Network	Check the connection with signal
Solid Red	Abnormal condition	configuration	cable and then do Comm Update.
		Network power source	Check network cable and power
		is not supplied from	supply.
		DeviceNet connector.	
Green		Device under self-	Wait for a moment
$\rightarrow$	Solf-diagnosis	diagnosis	
Flashing	Sell-ulagriosis		
Red			
		In the event of Identity	Normal response
		Communication	
Red		Request Message is	
$\rightarrow$	Communication	received at	
Flashing	Fault	communication Fault	
Green		status cased by failure	
		of Network Access	
		Passing.	

MS LED status

LED	Status	Cause	Trouble shooting
		DeviceNet	Checking whether inverter power On
		communication card has	or not.
Off	No Power	no 5V power source.	Checking the power source of
			DeviceNet communication card
			(5V).
Solid	Operational	Normal operation	
Green	Operational	Normal operation	-
		Interface communication	Checking connection status
Solid	Unrecoverable	between DeviceNet	between communication card and
Red	Fault	communication card and	inverter.
		inverter is not made up.	
Green		DoviceNet	
$\rightarrow$	Solf Toot		
Flashing			-
Red		sen-testing.	

### ➢ LED Tip

- ▲ In the event that Reset occurs;
  - ✓ MS (Module Status) LED flashes in Green Red at every 0.5 second at the beginning and the interface communication between DeviceNet communication card and inverter comes to normal state, it becomes solid Green.
  - ✓ Then, NS (Network Status) LED flashes in Green Red at every 0.5 second.
  - ✓ In the event there is no abnormality as a result of checking the redundant MAC ID, Network Status LED flashes in Green. It means this Device communication card is connected to the network in normal way, but communication is not made with any device.
  - ✓ If it fails to run as above, please check any of following three cases. If it runs in normal way, you may disregard the following cases.
  - ✓ If the interface communication between DeviceNet communication card and inverter doesn't in normal way, MS (Module Status) LED becomes solid Red. Be sure to check the connection between inverter and DeviceNet communication card first, and then turn on the inverter.

- ✓ In the event there is abnormality as a result of checking the redundant MAC ID, Network Status LED becomes solid Red. In this case, please configure MAC ID at the other value using keypad.
- ✓ In the event that the option board is in communication with the other Device, NS (Network Status) LED becomes solid Green.
- ▲ In the event of EMC (Explicit Message Connection) by EMC Scanner (Master)
  - ✓ Network Status LED becomes solid Green. If EMC setting is released here, it flashed in Green again after 10 seconds. Once EMC is achieved, I/O connection is available. In this case Network Status LED is still continued.
  - ✓ In the event that no communication is made within the time I/O connection is set, Time Out occurs, Network Status LED flashed in Red. (This Status can be changed into flashing Green again depending on the time setting of EMC)
  - ✓ In the event that EMC is connected but I/O connection is not connected, if wire came out, Green LED is still continued On status.

### 6. EDS (Electronic Data Sheets)

This file includes the information on the parameter of inverter. It is used when the user intends to control the parameters of MDLV-HP through the DeviceNet Manager program. In this case, it is necessary to install on PC the MDLV-HP-use EDS file that we provide. EDS file can be downloaded from LSIS website (<u>http://eng.lsis.biz</u>).

The name of EDS file: Lsis\_iS7\_AcDrive.EDS Revision: 2.01 The name of ICON: LSISInvDnet.ico

Paste the file of Lsis\_iS7\_AcDrive.EDS on EDS file folder by Master Configuration program and ICON files save at ICON folder.

Example) In case of SyCon program for XGT PLC series Paste the file of Lsis\_iS7\_AcDrive.EDS in DevNet folder and ICON files save in BMP folder.



# 7. Keypad Parameter associated with DeviceNet

Code	Name of Parameter	Initial Value	Range	Description
CNF-30	Ontion-1 Type	_	_	When MDLV-HP DeviceNet
				communication card is installed, it
			0. Keypad	To command inverter run with DeviceNet,
			1. Fx/Rx-1	it requires setting as 4. FieldBus.
	Cmd Sourco	1 Ev/Dv_1	2. Fx/Rx-2	
DIXV-0		1.1 //1\^-1	3. Int 485	
			4. FieldBus	
			5. PLC	
			0. Keypad-1	To command Inverter frequency with
			1. Keypad-2	DeviceNet, it requires setting as 8.
	DRV-7 Freq Ref Src	0. Keypad-1	2. V1	FieldBus.
			3. I1	
			4. V2	
DRV-7			5. I2	
			6. Int 485	
			7. Encoder	
			8. FieldBus	
			9. PLC	
COM 6				Indicates the version of DeviceNet
CONFO	FBus 5/W Ver	-	-	communication card
COM-7	FBus ID	1	0~63	-
	FBue		6. 125kbps	Requires setting at Baud Rate used in the
COM-8	FBUS	6. 125kbps	7 250kbps	network with which inverter is connected.
	Dauurale		8. 500kbps	
COM-9	FBus Led	-	-	-

Code	Name of Parameter	Initial Value	Range	Description
			0. 70	Set the value of input instance to be used in
			1. 71	At this parameter value is set, the Data Type
			2. 110	to be received (Master based) at the time of
COM 20	In Instance	0.70	3. 111	Poll I/O communication is decided. At the time of changing in Instance, DeviceNet
COM-29	in instance	0.70	4. 141	communication card is automatically reset. It
			5. 142	cannot be modified while the inverter runs.
			6. 143	
			7. 144	
COM-30	ParaStatus Num	-	-	When COM-29 In Instance is set at 141~144, the value of COM-30 ParaStauts Num is displayed automatically. This parameter value is changed depending on the value of COM- 29.
COM-31	Para Status-1	-	0~0xFFFF	It can be set/display in case of In Instance
COM-32	Para Status-2	-	0~0xFFFF	value between 141 ~ 144.
COM-33	Para Status-3	-	0~0xFFFF	
COM-34	Para Status-4	-	0~0xFFFF	
			0. 20	It set the value of Output Instance using at
			1. 21	parameter value, Data type to transmit
			2. 100	(Master-based) is decided in Poll I/O
COM-49	Out Instance	0.20	3. 101	Instance, DeviceNet communication card re-
		0.20	4. 121	set automatically. The parameter cannot be
			5. 122	modified during run status.
			6. 123	
			7. 124	
COM-50	Para Ctrl Num	-	-	When COM-49 Out Instance is set at 121~124, the value of COM-50 ParaStauts Ctrl Num is displayed automatically. This parameter value is changed depending on the value of COM-49.
COM-51	Para Control-1	-	0~0xFFFF	In event of the value of Out Instance between
COM-52	Para Control-2	-	0~0xFFFF	be set.
COM-53	Para Control-3	-	0~0xFFFF	
COM-54	Para Control-4	-	0~0xFFFF	
COM-94	Comm Update	0. No	0. No	It is used when DeviceNet communication card is initialized. If COM-94 is set with Yes, it

MDLV-HP DeviceNet Manual

	1. Yes	is	initialized	and	then	it	indicates	No
		au	tomatically.					

Code	Name of Parameter	Initial Value	Range	Description
PRT-12	Lost Cmd		0. None	In case of DeviceNet communication, it
	Mode		1. Free-Run	executes Lost Command of Communication
		0 None	2. Dec	when Command of Polling Communication
		U. None	3. Hold Input	Data is lost.
			4. Hold Output	
			5. Lost Preset	
PRT-13	Lost Cmd Time	1.0.000	0.1~120.0 sec	After I/O connection is disconnected, Lost
		1.0 Sec		Command will be occurred after setting time.
PRT-14	Lost Preset F		Start Freq~	If run method (PRT-12 Lost Cmd Mode) is set
			Max Freq	with No.5 Lost Preset when Speed Command
		0.00 HZ		is lost, protective function is operated and it is
				set the frequency to run continuously.

If you want to command for Run, Inverter Frequency by DeviceNet, DRV-06 Cmd Source, DRV-07 Freq Ref Src are set to FieldBus.

### (1) FBus ID (COM-7)

- ✓ FBus ID falls under MAC ID (Media Access Control Identifier) that is called in DeviceNet.
- ✓ As this value is an indigenous value by which each Device is discriminated in DeviceNet network, it is not allowed for different Devices to have same values.
- ✓ This value is preset as 1 at the factory. In that event that interface communication is in trouble between DeviceNet communication card and inverter, change the MAC ID.
- ✓ In the event of modifying MAC ID during operation, DeviceNet communication card will be automatically reset. This is because it is essential to check if Device Using MAC ID value newly set is on the network.
- ✓ In the event the preset MAC ID value is the one that has already been used by other Device, NS (Network Status) LED will be changed to solid Red. Here, MAC ID can be changed into the other value using keypad again. After that, NS is flashing in green, it means its normal operation.

### (2) FBus BaudRate (COM-8)

- ✓ In the event that the communication speed setting is not same as that used in the network, NS LED maintains Off state.
- ✓ In the event changing the Baud rate using keypad, in order for the changed Baud rate to influence the actual communication speed, it is necessary to send Reset service to the Identity Object of inverter through communication or reset the inverter.
- ✓ You may reset the inverter using COM-94 Comm Update.
- In the event that Network's Baud rate corresponds with Option card's Baud rate and MAC ID is only one, NS LED flashes in green.

### (3) FBus Led (COM-9)

- ✓ DeviceNet communication card has MS LED and NS LED only, but four LEDs are shown from COM-9 FBus LED using keypad. It displays the information of MS LED Red, MS LED Green, NS LED Red, NS LED Greed in the order of COM-09 LEDs (Left → Right).
  - ✓ If COM-9 is displayed as below, it indicates that currently MS LED RED and NS LED RED.

Example of COM-09 Fbus LED status)



MS LED Red	MS LED Green	NS LED Red	NS LED Green
ON	OFF	ON	OFF

#### (4) In Instance, Out Instance (COM-29, COM-49)

- ✓ In Instance, Out Instance is used in the Poll I/O data communication. Poll I/O connection is the Connection to communicate specific data between Scanner (Master) and Inverter.
- ✓ Type of data sent through Poll I/O is decided by the Assembly Instances (COM-29, COM-49).
- ✓ In case of instance 20, 21, 100, 101, 70, 71, 110 and 111, the amount of data sent to by Poll I/O communication is 4 bytes in both directions, and the communication cycle default value is 0 (zero).
- ✓ In case of the other instances, the amount of data sent by Poll I/O communication is 8 bytes in both directions.

- ✓ Assembly Instance can be broadly divided into Output and Input based on Scanner. That is, Input Data means the amount of data stored in Scanner. It means the value for inverter to feed back to scanner. On the contrary, Output Data means the amount of data supplied from scanner, which is a new command value for inverter.
- ✓ In the event of changing the value of In Instance or Out Instance, DeviceNet communication card is automatically reset.



Scanner (Master)

	From the viewpoint of	From the viewpoint of
	scanner	scanner
Input Assembly Data	Receiving data	Transmitting data
Output Assembly Data	Receiving data	Transmitting data

- ✓ In the event of setting COM-29 (In Instance) at 141 ~ 144, COM-30 ~ 38 are displayed. The using parameters are COM-30 ~ 34 from COM-30 ~ 38. In the event of setting the values other than 141 ~ 144, COM-30 ~ 38 are not displayed.
- ✓ Followings are the value of COM-30 Para Status Num automatically set and valid Parameter Status with Poll I/O communication depending on the value of In Instance set.

In	COM-								
141	1	0	×	×	×	×	×	×	×
142	2	0	0	×	×	×	×	×	×
143	3	0	0	0	×	×	×	×	×
144	4	0	0	0	0	×	×	×	×

- ✓ Out Instance can be applied in the same way as explained for In Instance.
- ✓ In the event of setting COM-49 Out Instance at 121 ~ 124, COM-50 ~ 58 are displayed. The using parameters are COM-50 ~ 54 from COM50 ~ 58. In the event of setting the value other than 121 ~ 124 to Out Instance, COM-50 ~ 58 are not displayed
- ✓ Followings are the value of COM-50 Para Ctrl Num automatically set and valid Parameter Control with communication depending on the value of Out Instance set.

Out	COM-								
121	1	0	×	×	×	×	×	×	×
122	2	0	0	×	×	×	×	×	×
123	3	0	0	0	×	×	×	×	×
124	4	0	0	0	0	×	×	×	×

### 8. Definition of Object Map

DeviceNet communication consists of the assemblies of Objects.

Following terminologies are used to explain the Objet of DeviceNet.

Terminology	Definition
Class	Assembly of Objects having similar function
Instance	Concrete expression of Object
Attribute	Property of Object
Service	Function supported by Object or Class

Followings are the definition of Object used in MDLV-HP DeviceNet.

Class Code	Object Class Name
0x01	Identity Object
0x03	DeviceNet
0x04	Assembly
0x05	Connection
0x28	Motor Data
0x29	Control Supervisor
0x2A	AC/DC Drive
0x64	Inverter

### 8. 1 Class 0x01 (Identity Object) Instance 1 (Entire device, host and adapter)

(1) Attribute

Attribute ID	Access	Attribute Name	Data	Attribute Value
			Length	
1	Get	Vendor ID	Word	250
1	Gei	(LS Industrial System)	vvoru	200
2	Get	Device Type (AC Drive)	Word	2
3	Get	Product Code	Word	11 <sup>(note 1)</sup>
		Revision		
4	Get	Low Byte - Major Revision	Word	(note 2)
		High Byte - Minor Revision		
5	Get	Status	Word	(note 3)
6	Cot	Sorial Number	Double	
6 Get			Word	
7	Cot	Product Name	12 Duto	MDHP
/	Gel		is byle	DeviceNet

(note1) Production Code 11 means MDLV-HP inverter.

(note2) Revision corresponds with the version DeviceNet communication card. High Byte means Major Revision and Low Byte means Minor Revision. For example, 0x0102 means 2.01. DeviceNet communication card version is displayed in Keypad COM-6 FBUS S/W Version.

### (note 3)

	Bit	0 (Owned)	8 (Recoverable Minor Fault)	Other Bits
		0: Device is not connected to	0: Normal state of Inverter Interface	
	Maaning	Master.	communication	Notournort
	Meaning	1: Device is connected to	1: Device is connected to 1: Abnormal state of Inverter	
		Master.	Interface communication	

### (2) Service

Service	Definition	Support	Support for
Code	Definition	for Class	Instance
0x0E	Get Attribute Single	No	Yes
0x05	Reset	No	Yes

### 8. 2 Class 0x03 (DeviceNet Object) Instance 1

(1) Attribute

Attribute	Access	Attribute Name		Data	Initial	Range	Description
ID	/ 100000		- taine	Length	Value	range	Decemption
							Address value of
1	Get/			Buto	1	0.63	DeviceNet
	Set	MACID		Dyte	'	0~03	communication
						card	
						0	125kbps
2	2 Get Baud Ra		Baud Rate (note 5)		0	1	250kbps
						2	500kbps
			Allocation			Bit 0	Explicit Message
		Allocation	Choice		-	Di+1	Pollod
5	Get	Get Information (note6)	Byte	Word		DILI	Folled
			Master's			0~63	Changed with
			MAC ID		-	255	Allocate only

(note4) MAC ID get/set its value in COM-07 FBus ID.

(note5) Bud Rate get/set the value of FBus Baudrate of COM-08.

(note6) It consists of 1 Word, Upper byte indicates MASTER ID connected and Lower byte indicates the type of communication between Master and Slave. Here, Master means not configuration, it means the device can communicate I/O communication, PLC etc. For reference, in the event of Master is not connected, it indicates 0xFF00 of Default Master ID. There is 2 type of communication type. In case of Explicit communication of non-periodic communication is possible, first bit is 1 and Polled communication of periodic communication is possible, second bit is 1. For example, PLC MASTER is 0 and if communication Explicit and Polled are possible, Allocation Information becomes 0x0003. If Master is not connected, it indicates 0xFF00.

#### (2) Service

Sonvice Code	Definition		Support for
Service Code	Demnition	for Class	Instance
0x0E	Get Attribute Single	Yes	Yes
0x10	Set Attribute Single	No	Yes
0x4B	Allocate Master/Slave Connection Set	No	Yes

0x4C	Release Group2 Identifier Set	No	Yes

## 8. 3 Class 0x04 (Assembly Object)

### In Instance 70/110

Instance	Byte	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0		
	0	-	-	-	-	-	Running	-	Faulted		
							Fwa				
	1		0x00								
		Speed actual (Low byte)									
70/110	2	Instance 70 - RPM unit									
		Instance 110 - Hz unit									
		Speed actual (High byte)									
	3		Instance 70 - RPM unit								
				l	nstance 1'	10 - Hz un	it				

## Detailed description of Instance 70/110

		Faulted	Signal on the occurrence of inverter Trip		
	Bit0		0: Inverter in normal condition		
Duto 0			1: Occurrence of inverter Trip		
вује о	Bit2	Bunning	Indicates the information if inverter runs in forward direction		
		Fwd	0: Not in forward direction.		
			1: In forward direction		
			Instance 70: Indicates the current information on inverter running		
Byte 2	Speed	reference	speed in [rpm].		
Byte 3	Speed reference		Instance 110: Indicates the current information on inverter running		
			speed in [Hz].		

Bit0

Faulted

#### Instance Byte Bit7 Bit6 Bit5 Bit4 Bit3 Bit2 Bit1 Ref From Ctrl Running Running At 0 Ready \_ From Net Ref. Rev Fwd Net 0x00 1 Speed actual (Low byte) 71/111 Instance 71 - RPM unit 2 Instance 111 - Hz unit Speed actual (High byte) 3 Instance 71 - RPM unit

Instance 111 - Hz unit

#### In Instance 71/111

#### **Detailed description of Instance 70/110**

			Signal on the occurrence of inverter Trip
	Bit0	Faulted	0 : Inverter in normal condition
			1 : Occurrence of Inverter Trip
		Dunning	Indicates the information if Inverter runs in forward direction.
	Bit2	Running	0 : Not in forward direction.
		FWQ	1 : In forward direction
		Dunning	Indicates the information if Inverter runs in reverse direction.
	Bit3	Running Rev	0 : Not in reverse direction.
			1 : In reverse direction
Byte 0	D:#4	Ready	Indicates the status information if Inverter is ready to run
			0 : Inverter is not ready to run
	DII4		1 : Inverter is ready to run
			When the power of inverter is ON, this value always becomes 1.
			Indicates if the current run command source is communication.
			0: In case inverter run is commanded from the other source than
	DitE	Ctrl From	communication
	BI[2	Net	1: In the event inverter run command is from communication, this
			value becomes 1 if the set value of DRV-06 Cmd Source is
			FieldBus.

			Indicates if the current frequency command source is
			communication.
		Def From	0: In case inverter frequency command is from the other source
	Bit6	Net	than communication
		inet	1: In the event inverter frequency command is from
			communication, this value becomes 1 if the set value of DRV-07
			Freq Ref Source is FieldBus.
			Indicates the current frequency reached the Reference
	D:+7	At Dof	frequency.
	DIL	ALKEI	0 : Current frequency fails to reach Reference frequency.
			1 : Current frequency reached Reference frequency
			Instance 71 : Indicates the current information on inverter
Byte 2	Sno		running speed in [rpm].
Byte 3	Spee		Instance 111 : Indicates the current information on inverter
			running speed in [Hz]

## Table of other Attribute associated with In Instance (70, 71, 110, 111)

Nome	Description	Related Attribute			
Name	Description	Class	Instance	Attribute	
Faulted	Inverter error occurs in interface communication or inverter Trip.	0x29	1	10	
Running Fwd	Motor is running in forward direction.	0x29	1	7	
Running Rev	Motor is running in reverse direction.	0x29	1	8	
Ready	Motor is ready to run.	0x29	1	9	
Ctrl From Net	Run/Stop control Signal 1 : DeviceNet is the inverter run command source.	0x29	1	15	
Ref From Net	Speed control command signal 1 : DeviceNet is the inverter run command source.	0x2A	1	29	
At Reference	Checks if the current frequency corresponds with the object frequency 1 : Command frequency is same as the current frequency	0x2A	1	3	
Drive State	Current Motor State	0x29	1	6	
Speed Actual	Indication the current run frequency	0x2A	1	7	

#### Instance 141/142/143/144

When In Instance is set at 141, 142, 143 and 144, Receive (Master-based) Poll I/O data information is not fixed, and the address of the data that the user intends to use in COM-31~34 is configured, allowing the user flexibility.

When In Instance 141, 142, 143 and 144, DeviceNet communication card sends Master each data in 2 Bytes, 4 Bytes, 6 Bytes, 8 Bytes. The Byte of the data to be sent is fixed depending on the set value of In Instance. For example, If In Instance is set at 141, it transmits the data in 2 Bytes. But In Instance is set at 143, it transmits the data in 6 Bytes.

Instance		ce	Byte	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0				
		1	1 1 1	0	Lo	Low Byte of the Address set at COM-31 Para State-1									
			141	1	Hig	h Byte o	of the Ac	ldress s	et at CC	)M-31 P	ara Stat	e-1			
		1	140	2	Lo	w Byte c	of the Ad	dress se	et at CO	M-32 Pa	ara Stat	e-2			
			142	3	Hig	h Byte o	of the Ac	ldress s	et at CC	M-32 P	ara Stat	e-2			
		1	142	4	Lo	w Byte c	of the Ad	dress se	et at CO	M-33 Pa	ara Stat	e-3			
		I	143	5	Hig	h Byte o	of the Ac	ldress s	et at CC	)M-33 P	ara Stat	e-3			
		1	1 / /	6	Lo	w Byte c	of the Ad	dress se	et at CO	M-34 Pa	ara Stat	e-4			
		I	144	7	Hig	h Byte o	of the Ac	ldress s	et at CC	M-34 P	ara Stat	e-4			

### Output Instance 20/100

Instance	Byte	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0				
	0	_	_	_	_	_	Fault	_	Run				
	0	-				-	Reset	_	Fwd				
	1												
		Speed reference (Low byte)											
20/100	2		Instance 20 - RPM unit										
				Ir	stance 10	00 - Hz ur	nit						
				Spee	ed referen	ce (High	byte)						
	3		Instance 20 - RPM unit										
				Ir	nstance 10	00 - Hz ur	nit						

### Detailed description of Instance 20/100

		Run Fwd	Commands Forward Direction Run.
	Bit0		0 : Stop forward direction run
			1 : Forward direction run command
Buto 0	Bit2		Resets when error occurs. It happens only when inverter trip
Byle U		Fault	occurs.
			0: It doesn't adversely affect the inverter. (You may not be
		Resei	concerned about it)
			1: performs Trip Reset.
Byte 2	Cread	reference	Instance 20: Commands the inverter speed in [rpm]
Byte 3	B Speed reference		Instance 100: Commands the inverter speed in [Hz].

### Output Instance 21/101

Instance	Byte	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0			
	0						Fault	Run	Run			
	0	-	-	-		_	Reset	Rev	Fwd			
	1	_										
		Speed reference (Low byte)										
21/101	2	Instance 21 - RPM unit										
				Ir	nstance 10	01 - Hz ur	nit					
			Speed reference (High byte)									
	3	Instance 21 - RPM unit										
				Ir	nstance 10	01 - Hz ur	nit					

### Detailed description of Instance 21/101

		Run Fwd	Command forward direction run.
	Bit0		0 : Stop forward direction run
			1 : Forward direction run command
			Commands reverse direction run.
	Bit1	Run Rev	0 : Stop reverse direction run
Byte 0			1 : Reverse direction run command
		Fault	Reset when error occurs. It happens only when inverter Trip
			occurs.
	Bit2		0 : It doesn't affect the inverter. (You may not be concerned
		Resei	about it.
			1 : Performs Trip reset
Byte 2	Speed	reference	Instance 21 : Commands the inverter speed in [rpm].
Byte 3	Speed reference		Instance 101 : Commands the inverter speed in [Hz].

 Table of other Attribute associated with In Instance (20, 21, 100, 101)

Nomo	Description	Related Attribute				
Name	Description	Class	Instance	Attribute ID		
Run Fwd (note6)	Forward Run Command	0x29	1	3		
Run Rev (note6)	Reverse Run Command	0x29	1	4		
Fault reset (note6)	Fault Reset Command	0x29	1	12		
Speed reference	Speed Command	0x2A	1	8		

note6) Refer to Drive Run and Fault of 6.6 Class 0x29 (Control Supervisor Object).

#### Out Instance 121/122/123/124

When Out Instance is set at 121, 122, 123 and 124, Send (Master-based) Poll I/O Data Information is not fixed, but the address of the data that the user intends to for COM-51~54 is set, giving the user flexibility.

At the time of using Out Instance 121, 122, 123 and 124, DeviceNet communication card receives from Master the data of 2Bytes, 4Bytes, 6Bytes and 8Bytes. However, the number of information received is decided depending on the set value of Out Instance. For example, if Out Instance is set at 122, the DeviceNet communication card receives the data value of 4Bytes.

Instance		ince	Byte	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0		
			121	0		Low Byte of the Address set at COM-51 Para State-1							
				1		High I	Byte of t	he Addr	ess set a	at COM	-51 Para	a Control1	
			100	2		Low E	Byte of th	ne Addre	ess set a	t COM-	52 Para	Control-2	
			122	3		High E	Byte of tl	he Addre	ess set a	at COM-	52 Para	Control-2	
			400	4		Low E	Byte of th	ne Addre	ess set a	t COM-	53 Para	Control-3	
			123	5		High E	Byte of tl	he Addre	ess set a	at COM-	53 Para	Control-3	
		40.4		6		Low E	Byte of th	ne Addre	ess set a	t COM-	54 Para	Control-4	
		124		7		High E	Byte of tl	he Addre	ess set a	at COM-	54 Para	Control-4	

### 8.4 Class 0x05 (DeviceNet Connection Object)

## (1) Instance

Instance	Instance Name
1	Predefined EMC
2	Poll I/O
6, 7, 8, 9, 10	Dynamic EMC

## (2) Attribute

	Acc	ess		
Attribute ID	Established/ Timed Out	Established/ Deffered delete	Attribute Name	
1	Get	Get	State	
2	Get	Get	Instance type	
3	Get	Get	Transport Trigger Class	
4	Get/Set	Get	Produced Connection ID	
5	Get/Set	Get	Consumed Connection ID	
6	Get	Get	Initial Comm Characteristics	
7	Get	Get	Produced Connection Size	
8	Get	Get	Consumed Connection Size	
9	Get/Set	Get/Set	Expected Packet Rate	
12	Get/Set	Get/Set	Watchdog Timeout Action	
13	Get	Get	Produced Connection Path Length	
14	Get	Get	Produced Connection Path	
15	Get	Get	Consumed Connection Path Length	
16	Get	Get	Consumed Connection Path	
17	Get/Set	Get	Production Inhibit Time	

## (3) Service

Service	Definition	Support	Support for
Code	Deminition	for Class	Instance
0x0E	Get Attribute Single	No	Yes
0x05	Reset	No	Yes
0x10	Set Attribute Single	No	Yes

## 8.5 Class 0x28 (Motor Data Object) Instance 1

(1) Attribute

Attribute ID	Access	Attribute Name	Range	Definition
3	Get	Motor Type	7	Squirrel-cage induction motor
6	Get/Set	Motor Rated Curr	0~0xFFFF	[Get] Reads the value of BAS-13 Rated Curr [Set] Set value is reflected to BAS-13 Rated Curr Scale 0.1
7	Get/Set	Motor Rated Volt	0~0xFFFF	[Get] Reads the value of BAS-15 Rated Volt. [Set] Set value is reflected to BAS-15 Rated Volt. Scale 1

## (2) Service

Service	Definition	Support	Support for
Code	Deminition	for Class	Instance
0x0E	Get Attribute Single	No	Yes
0x10	Set Attribute Single	No	Yes

## 8.6 Class 0x29 (Control Supervisor Object) Instance 1

(1) Attribute

Attribute ID	Access	Attribute Name	Initial value	Range	Definition
2	Get /	Forward Dup Cred	0	0	Stop
3	Set	Forward Run Cind.	0	1	Forward Direction Run
	Get /	David David	0	0	Stop
4	Set	Reverse Run Cma.	0	1	Reverse Direction Run
5	Get	Net Control	0	0	Run Command with the Source other than DeviceNet communication
				1	Run Command with DeviceNet communication Source
				0	Vendor Specific
				1	Startup
				2	Not Ready (State of resetting)
				3	Ready (State of Stopping)
6	Get	Drive State	3	4	Enabled (Acceleration, Constant Speed)
				5	Stopping (State of Stopping)
				6	Fault Stop
				7	Faulted (Trip Occurred)
7	Cat	Dupping Forward	0	0	State of Stopping
1	Gei	Running Forward	0	1	State of running in forward direction
o	Cot	Pupping Poverse	0	0	State of Stopping
0	Gei	Running Reverse	0	1	State of running in reverse direction
				0	State of resetting or Trip occurred.
9	Get	Drive Ready	1	1	Normal condition where inverter can run
10	Cat		0	0	State that Trip doesn't occur at present
10	Gei	Drive Fault	0	1	State that Trip occurred at present. Falls under the case of Latch Trip
	Get /		_	0	-
12	Set	Drive Fault Reset	0	1	Trip Reset to release trip after the occurrence of Trip
13	Get	Drive Fault Code	0		Refer to the Table of Drive Fault Code as below
14	Get	Control From Net. (DRV-06 Cmd	0	0	Run Command with the Source other than DeviceNet communication
		Source)		1	communication Source

Run1	Run2	Trigger Event	Run Type
0	0	Stop	NA
0 -> 1	0	Run	Run 1
0	0->1	Run	Run 2
0 -> 1	0->1	No Action	NA
1	1	No Action	NA
1->0	1	Run	Run2
1	1->0	Run	Run1

#### Inverter Operation with Forward Run Cmd. and Reverse Run Cmd.

In the above table, Run1 indicates Forward Run Cmd. And Run 2 indicates Reverse Run Cmd. That is, Option board will be command to inverter at the moment that the status is changed from 0 (FALSE) to 1 (TRUE). The value of Forward Run Cmd. indicates the value of option board Run Command not current status of inverter run.

### **Drive Fault**

Drive Fault becomes TRUE when Inverter has a Trip. Drive Fault Codes are as follows.

### **Drive Fault Reset**

Inverter commands TRIP RESET when Drive Fault Reset is becomes 0 -> 1; that is FALSE -> TRUE. In the event of 1 (TRUE) command is repeated at 1 (TRUE) status, TRIP RESET command is not valid to inverter Trip. TRIP RESET command can be valid to command 0 (FAULT) at 1 (TRUE) status and then command 1 (TRUE).

### **Drive Fault Code**

Fault Code Number	Description				
0x0000	None				
	Ethermal	Out Phase Open	InverterOLT		
	InPhaseOpen	ThermalTrip	UnderLoad		
0x1000	ParaWriteTrip	IOBoardTrip	PrePIDFail		
	OptionTrip1	OptionTrip2	OptionTrip3		
	LostCommand	UNDEFINED	LostKeypad		
0x2200	OverLoad				
0x2310	OverCurrent1				
0x2330	GFT				
0x2340	OverCurrent2				
0x3210	OverVoltage				
0x3220	LowVoltage				
0x2330	GroundTrip				
0x4000	NTCOpen				
0x4200	OverHeat				
0x5000	FuseOpen	HWDiag			
0x7000	FanTrip				
0x7120	No Motor Trip				
0x7300	EncorderTrip				
0x8401	SpeedDevTrip				
0x8402	OverSpeed				
0x9000	ExternalTrip	BX			

## (2) Service

Service	Definition	Support	Support for
Code	Demnition	for Class	Instance
0x0E	Get Attribute Single	No	Yes
0x10	Set Attribute Single	No	Yes

## 8.7 Class 0x2A (AC Drive Object) Instance 1

(1) Attribute

Attribut e ID	Access	Attribute Name	Range	Definition
3	Get	At Reference	0	Frequency command is not set by Keypad.
Ū			1	Frequency command is set by Keypad.
4	Get	Net Reference	0	Frequency command is not set by Fieldbus.
			1	Frequency command is set by Fieldbus.
			0	Vendor Specific Mode
			1	Open Loop Speed (Frequency)
6	Get	Drive Mode (note7)	2	Closed Loop Speed Control
			3	Torque Control
			4	Process Control (e.g.PI)
7	Get	SpeedActual	0~24000	Indicates current output frequency in [rpm] unit.
8	Get / Set	SpeedRef	0~24000	Commands the target frequency in [rpm] unit. It can be applied with the setting 8.FieldBus of DRV-07 Freq Ref Src. Range Error will be occurred when speed command is set larger than MAX. Frequency of inverter.
9	Get	Actual Current	0~111.0 A	Monitor the present current by 0.1 A unit.
	Cat	Ref.From	0	Frequency command source is not DeviceNet communication.
29	Get	Network	1	Frequency command source is DeviceNet communication.
100	Get	Actual Hz	0~400.00 Hz	Monitor the current frequency (Hz unit).
101	Get / Set	Reference Hz	0~400.00 Hz	Command frequency can be set by communication when DRV-07 Freq Ref Src is set 8.FieldBus. Range Error will be occurred when speed command is set larger than MAX. Frequency of inverter.
102	Get / Set	Acceleration Time	0~6000.0 sec	Set/Monitor the inverter acceleration time.
103	Get /Set	Deceleration Time	0~6000.0 sec	Set/Monitor the inverter deceleration time.

(note7) It related with DRV-10 Torque Control, APP-01 App Mode. If DRV-10 Torque Control is set to Yes, Drive Mode becomes "Torque Control". If APP-01 App Mode is set to Proc PID, MMC, Drive Mode becomes "Process Control (e.g.PI)".

(note8) It is related with DRV-03 Acc Time.

(note9) It is related with DRV-04 Dec Time.

#### (2) Service

Service	Definition	Support	Support for
Code	Deminition	for Class	Instance
0x0E	Get Attribute Single	Yes	Yes
0x10	Set Attribute Single	No	Yes

#### 8.8 Class 0x64 (Inverter Object) – Manufacture Profile

(1) Attribute

Instance	Access	Attribute Number	Attribute Name	Attribute Value
2 (DRV Group)				
3 (BAS Group)				
4 (ADV Group)				
5 (CON Group)				
6 (IN Group)			LID Key med Title	Setting range of
7 (OUT Group)	Get/Set	Identical with HP		HP Parameter
8 (COM Group)		Manual Code		(Refer to HP
9 (APP Group)			Mariual)	Manual)
10 (AUT Group)				
11 (APO Group)				
12 (PRT Group)				
13 (M2 Group)				

(2) Service

Service	Definition	Support	Support for
Code	Dennition	for Class	Instance
0x0E	Get Attribute Single	Yes	Yes
0x10	Set Attribute Single	No	Yes

\* Read Only which is the parameter attribute of inverter is not support the Set Service.

# Warranty

Product	Regal Australia		Installation	
Name	Option Ca	rd	Date	
Model	MDLV-HP D	eviceNet	Warranty	
Name	Communica	tion Card	Period	
	Name			
Customer	Address			
	Tel.			
	Name			
Sales Office	Address			
	Tel.			

#### Note

This product has been manufactured through the strict QC control and inspection of Regal Australia. Warranty period is 12 months from date of Sale, subject to Regal Australia standard terms and conditions of sale

- In-warranty service information
  - If the defective part has been identified under normal and proper use within the guarantee term, contact your local authorized MD distributor or MD Service center.
- Out-of-warranty service information
  - The guarantee will not apply in the following cases.
  - > Troubles are attributable to a user's intentional negligence or carelessness.
  - Damage was caused by abnormal voltage and peripheral devices' malfunction (failure).
  - Damage was caused by natural disasters (earthquake, fire, flooding, lightning and etc).
  - When MD nameplate is not attached.

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